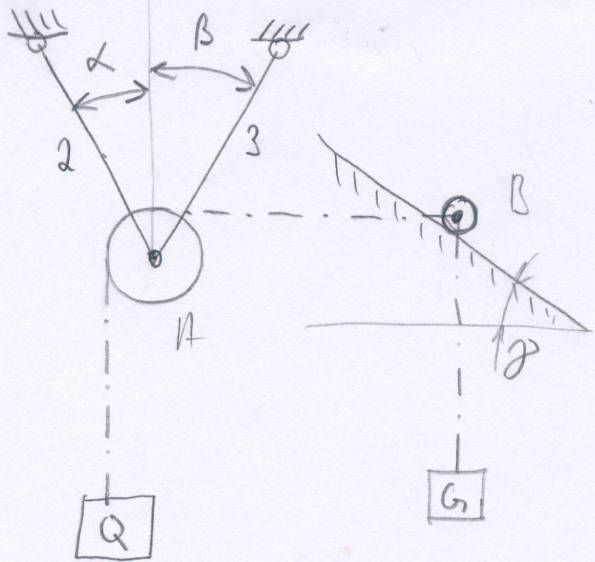


PŘÍKLAD HB-02

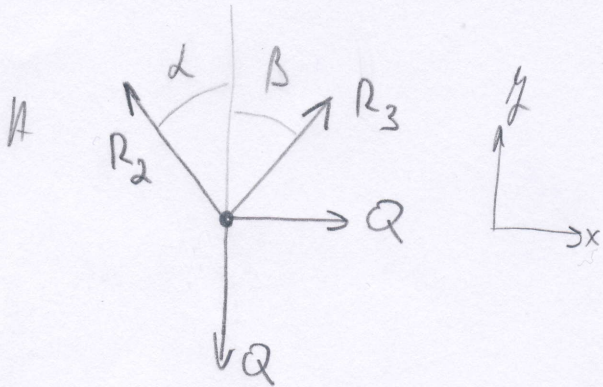


D:  $\alpha, \beta, \gamma$

V: a) Q + reakce  
b) G

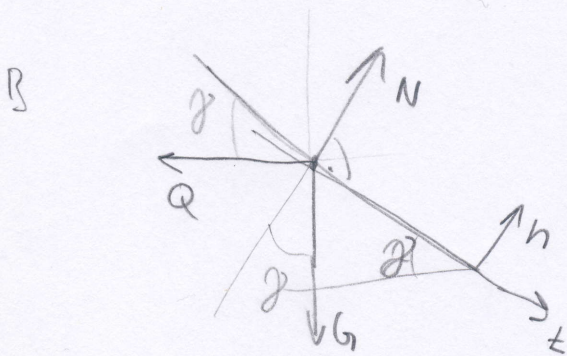
U: a) G + reakce

b) Q + reakce



$$x: Q + R_3 \sin \beta - R_2 \sin \alpha = 0 \quad 1)$$

$$y: R_3 \cos \beta + R_2 \cos \alpha - Q = 0 \quad 2)$$



$$z: G \sin \gamma - Q \cos \gamma = 0 \quad 3)$$

$$n: N - G \cos \gamma - Q \sin \gamma = 0 \quad 4)$$

4 NEZMĚNÉ:  $G(Q), N, R_2, R_3$

4 ROVNICE

a)

$$\Rightarrow G = Q \cot \gamma$$

$$N = G \cos \gamma + Q \sin \gamma = Q (\cot \gamma \cdot \cos \gamma + \sin \gamma) =$$

$$= Q \left( \frac{\cos^2 \gamma}{\sin \gamma} + \sin \gamma \right) = Q \left( \frac{\cos^2 \gamma + \sin^2 \gamma}{\sin \gamma} \right) = \frac{Q}{\sin \gamma}$$

$\Rightarrow$  PRO  $\gamma = 0$  NEMÁ PŘEŠENÍ

PRO  $\gamma = \frac{\pi}{2}$   $G = 0$ ;  $N = Q$

$R_2$  A  $R_3$  URČÍME  
Z ROVNIC 1), 2)



$$\begin{bmatrix} -\sin\alpha & \sin\beta & 0 & 0 \\ \cos\alpha & \cos\beta & 0 & 0 \\ 0 & 0 & 0 & \sin\gamma \\ 0 & 0 & 1 & -\cos\gamma \end{bmatrix} \times \begin{bmatrix} R_2 \\ R_3 \\ N \\ G \end{bmatrix} = Q \begin{bmatrix} -1 \\ 1 \\ \cos\gamma \\ \sin\gamma \end{bmatrix}$$

$$\Rightarrow R_2, R_3, N, G$$

b)

$$\begin{bmatrix} R_2 & R_3 & N & Q \\ -\sin\alpha & \sin\beta & 0 & 1 \\ \cos\alpha & \cos\beta & 0 & -1 \\ 0 & 0 & 0 & -\cos\gamma \\ 0 & 0 & 1 & -\sin\gamma \end{bmatrix} \times \begin{bmatrix} R_2 \\ R_3 \\ N \\ Q \end{bmatrix} = G \begin{bmatrix} 0 \\ 0 \\ -\sin\gamma \\ \cos\gamma \end{bmatrix}$$