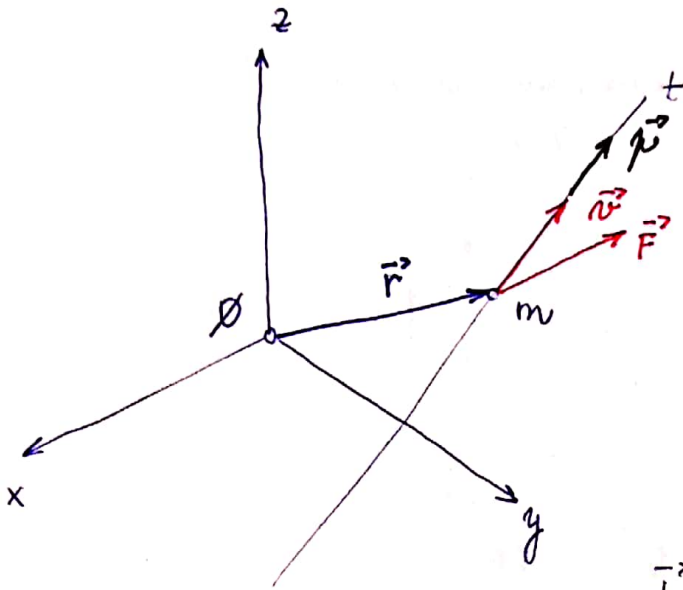


### 3) LAW OF CHANGE OF ANGULAR MOMENTUM



$\vec{v}$  ... velocity of particle  
 $\vec{r}$  ... displacement vector  
 $\vec{p} = m \cdot \vec{v}$   
 $m$  ... mass of particle

$$\vec{p} = m \vec{v} \quad / \quad \vec{r} \times$$

$$\vec{r} \times \vec{p} = \vec{r} \times (m \vec{v})$$

$\vec{L}$  ... angular momentum

$$\vec{L} = \vec{r} \times (m \vec{v}) \quad / \quad \frac{d}{dt}$$

$$\frac{d\vec{L}}{dt} = \underbrace{\frac{d\vec{r}}{dt}}_{\vec{v}} \times (m \vec{v}) + \vec{r} \times m \underbrace{\frac{d\vec{v}}{dt}}_{\vec{a}}$$

$$\frac{d\vec{L}}{dt} = m \cdot \underbrace{(\vec{v} \times \vec{v})}_{\vec{0}} + \underbrace{\vec{r} \times \vec{F}}_{\vec{M}}$$

$$\boxed{\frac{d\vec{L}}{dt} = \vec{M}}$$

differential form  
/dt

$$\int_{\vec{L}_1}^{\vec{L}_2} d\vec{L} = \int_{t_1}^{t_2} \vec{M} dt$$

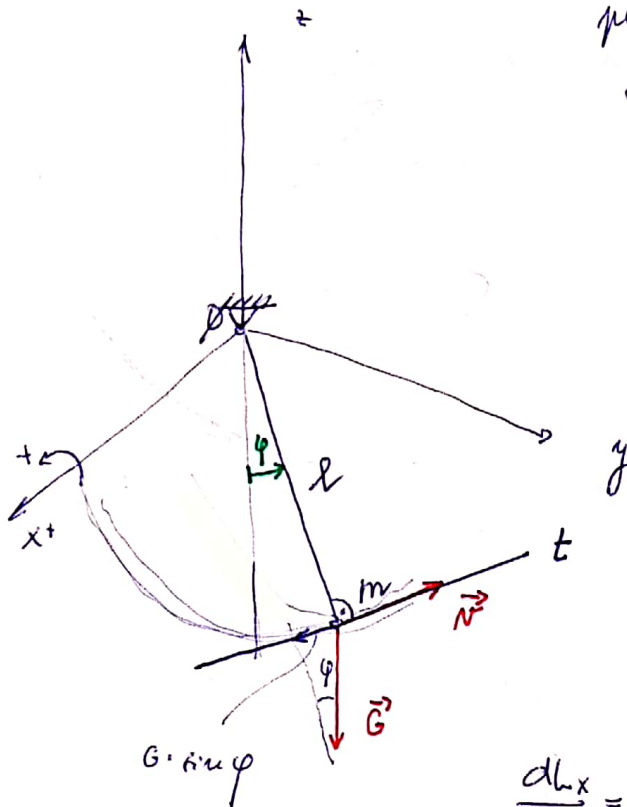
impulse  
of moment

$$\boxed{\int_{t_1}^{t_2} \vec{M} dt = \vec{L}_2 - \vec{L}_1}$$

integral form

$$\vec{L}_2 - \vec{L}_1 = \vec{r}_2 \times (m \vec{v}_2) - \vec{r}_1 \times (m \vec{v}_1) = m (\underbrace{\vec{r}_2 \times \vec{v}_2}_{\vec{p}_2} - \underbrace{\vec{r}_1 \times \vec{v}_1}_{\vec{p}_1})$$

example: Mathematical pendulum



pendulum makes motion  
in plane  $(y, z)$

$$\frac{d\vec{L}}{dt} = \vec{M} \quad (*)$$

for 1D case:

$$\frac{dL_x}{dt} = M_x \quad (*')$$

angular momentum

$$L_x = \underline{r \cdot m \cdot v} =$$

$$= \underline{r \cdot m \cdot l \dot{\varphi}}$$

$$v = l \dot{\varphi}$$

$$\dot{\varphi} = \frac{d\varphi}{dt} = \omega$$

$$\ddot{\varphi} = \frac{d\dot{\varphi}}{dt} = \alpha$$

$$\frac{dL_x}{dt} = \underline{m \cdot l^2 \ddot{\varphi}}$$

$$M_x = -G \sin \varphi \cdot l$$

substitution in  $(*)'$ :

$$(G = mg)$$

$$m \cdot l^2 \ddot{\varphi} = -mg \cdot l \sin \varphi \quad | \cdot \frac{1}{l}$$

$$\ddot{\varphi} + \frac{g}{l} \sin \varphi = 0$$

principal equ.  
of motion of  
math. pendulum

$$\varphi(t) = \dots$$